Application Report SPRACC3-January 2018

Flashing Utility - mflash

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ABSTRACT

This application report focuses mainly on the procedure to flash the Secondary BootLoader and AppImage into TDA3xx Systems. sbl_mflash algorithms are not in the scope of this document. But the procedure to configure and build the executable is defined here.

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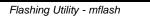
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1 Introduction

This application report provides detailed procedure for flashing the binary images to QSPI Flash memory using the Universal Asynchronous Receiver/Transmitter (UART) interface for the TDA2xx and TDA3xx Boards. Generally, the MMC/SD boot mode can be used to boot the fresh production board/EVM. In case there is not an external MMC/SD card available as part of production EVM or final product, this application report will be useful to flash the images to the factory boards using the UART boot mode of TDA3xx, respectively.

2 Need of Multicore Flashing Utility

Typically, there are multiple interfaces to boot from when it is about Evaluation Module (EVMs) but for production system/target boards at customer places, interfaces are very limited. Thus, in order to make it easy and fast for customer to flash binaries to production device a Windows/Linux based utility is needed. mflash currently supports flashing on TDA3x systems via UART but could be extended similarly for other platforms, too.



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TRUMENTS

ADAS Software



3 Brief Overview of its Working

- ROM bootloader runs and checks the sysboot switch settings to find peripheral boot mode
- · Receives the peripheral boot mode request instruction via UART3
- Receives the sbl_mflash via UART3 and puts it into the on-chip memory
- sbl_mflash starts to execute and interacts with the PC to download the sbl and AppImage into the Flash memory.

4 System/Software Setup

4.1 System Requirements

The executable was created and tested on:

- Windows 10 based 64 bit PC
- Ubuntu 16.04.2 LTS 64 bit PC

4.2 Windows

4.2.1 Finding the Correct COM Port Using Tera-Term

Tera term is one of the serial port communication application for windows which can be downloaded and installed. Connect a serial cable to the UART port of the EVM and the other end to the serial port of the PC. It will detect four UART ports; you need to select the third Port of EVM with the following settings that can be setup from Setup \rightarrow Serial Port to the following:

Tera Term: Serial port setup		×		
Port:	СОМ6 -	ОК		
Baud rate:	115200 -			
Data:	8 bit 🔹	Cancel		
Parity:	even 🔹			
Stop:	1 bit 🔹	Help		
Flow control:	none 🔻			
Transmit delay O msec/char O msec/line				

Figure 1. Tera Term Setup Window



To find the correct COM Port number for the peripheral boot put the board in UART boot mode by changing the SYSBOOT switch SW2 to [00010000][10000001] for TDA3xx board.

With correct settings, it should continuously display AL! on the TeraTerm.

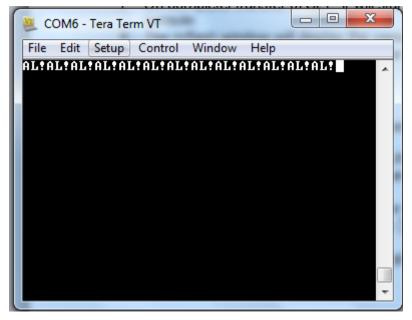


Figure 2. Serial Output When Booting in UART Boot Mode

Note the COM Port number. For example if COM6 displays AL! then the COM Port number is 6. This is also an assurance that the switch settings on the EVM are correct. Disconnect and close TeraTerm.

4.2.2 Configuring the Flashing Script

Since the flashing tool takes all the parameters via command line, there is a configuration script in the same folder mflash_run_config.bat that can be modified to flash every time. The first 6 lines can be changed according to the usage.

Its structure is as follows:

```
SET sbl_mflash=<path_to_sbl_mflash>
SET appimage_location=<path_to_AppImage>
SET appimage_offset=<AppImage offset>
SET sbl_location=<path_to_sbl>
SET sbl_offset=<sbl offset>
SET uart_port_number=<port_number>
```

A typical example where all the files are in the same folder as the mflash executable would be:

```
SET sbl_mflash="sbl_mflash"
SET appimage_location="AppImage_BE"
SET appimage_offset="0x80000"
SET sbl_location="sbl"
SET sbl_offset="0x00"
SET uart_port_number="5"
```

The last line executes the mflash executable with the above given parameters:

```
mflash -M %sbl_mflash% -P %uart_port_number% -F %appimage_location% %appimage_offset% -
F %sbl_location% %sbl_offset% -C
```



4.3 Linux

4.3.1 Finding the Correct COM Port Using Minicom

Use minicom on Linux to find the correct COM port. Ports are usually named as /dev/ttyUSBx where x is the port number required. Usually it is the third port on the list. One way to look at all the serial communication devices connected to the system is to look into the /dev/ directory and the ports would appear as files named as /dev/ttyUSBx where x is the required port number.

\$ cd /dev/

\$ ls

In the list of connected serial ports, the third port is required port ID. It might be different on different systems, so check it once to be sure.

Configure the Minicom Serial Port with the following setting:

Parameter	Value
Baud	115200
Data	8 bit
Parity	Even
Stop Bit	1 bit
Flow Control	None

Table 1	Serial	Port	Configuration
---------	--------	------	---------------

Speed Parity Da A: <next> L: None S: B: <prev> M: Even T: C: 9600 N: Odd U: D: 38400 O: Mark V:</prev></next>	ta
B: <prev> M: Even T: C: 9600 N: Odd U:</prev>	
C: 9600 N: 0dd U:	5
	б
1. 39400 O. Mark V.	7
0. naik v.	8
E: 115200 P: Space	
Stopbits	
N; 1 Q: 8-N-1	
X: 2 R: 7-E-1	

Figure 3. minicom Serial Communication Configuration



System/Software Setup

When connected to the correct COM Port with the proper switch settings, the terminal should continuously display the printable part of the ASIC id which should be "AL!". Also minicom also prints the non-printable characters so AL! is visible but along with other characters.

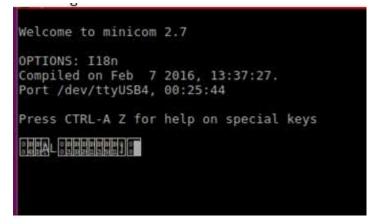


Figure 4. Serial Output in Minicom on Linux

If zoomed enough, it looks correct:



Figure 5. Serial Output on Minicom (Zoomed)

Note the Port number that displays the correct id. This is also an assurance that the switch settings on the EVM are correct.

4.3.2 Configuring the Flashing Script

Since the flashing tool takes all the parameters via command line, there is a configuration script that can be modified to flash every time. The first six lines can be changed according to the usage.

Its structure is as follows:

```
sbl_mflash=<path_to_sbl_mflash>
appimage_location=<path_to_AppImage>
appimage_offset=<AppImage offset>
sbl_location=<path_to_sbl>
sbl_offset=<sbl offset>
uart_port_number=<port_number>
```

A typical example where all the files are in the same folder as the mflash executable would be:

```
sbl_mflash="sbl_mflash"
appimage_location="AppImage_BE"
appimage_offset="0x80000"
sbl_location="sbl"
sbl_offset="0x00"
uart_port_number="4"
```

The last line executes the mflash executable with the above given parameters:

System/Software Setup



www.ti.com

4.4 Building sbl_mflash

To build sbl_mflash (sbl that is sent by PC side mflash utility to ROM code over uart):

- 1. Go to pdk/packages/ti/build
- 2. Use following build command
 \$ make -s -j sbl BOARD=tda3xx-evm BOOTMODE=uart SBL_TYPE=mflash
- 3. Go to pdk/packages/ti/boot/sbl auto/tools/mflash
 - a. Ensure paths and profile mentioned in the script is right
 - b. Execute sbl_mflash_create_tda3xx.sh / .bat
- 4. On success pdk/packages/ti/boot/sbl_auto/tools/mflash/mflash_tda3xx directory will be created.
- 5. sbl_mflash is created in mflash_tda3xx.

4.5 Building AppImage for TDA3xx and TDA2xx

The procedure to build AppImage and sbl_qspi can be done as described in VisionSDK_UserGuide_TDAxxx.pdf.

4.6 Building mflash for TDA3xx

To build mflash in any environment a gcc compiler is required. Go to the directory pdk/packages/ti/boot/sbl_auto/tools/mflash and run the following command to build the executable named "mflash".

\$ gcc -o mflash mflash_uart.c

The executable mflash will be created in the same directory.

5 Flashing TDA3xx via UART Interface

To Flash sbl and AppImage in TDA3xx in Peripheral Boot Mode:

- 1. Build sbl_mflash and mflash for TDA3xx if not already built as described above.
- 2. Make the following connections:
 - a. Connect a serial cable to the UART port of the EVM and the other end to the serial port of the PC
 - b. Change the sysboot switches SW2[0:7] and SW3[8:15] to [00010000][100000001] and SW8 to [01000001]
 - c. Connect and Power Reset the board SW4
- 3. Note the appropriate COM Port as described previously.
- 4. Reset the board.
- 5. 5. Run the mflash_run_config.sh(.bat) file after providing appropriate parameters, or provide your own command in the following syntax:

<pre>\$./mflash -M <sbl_mflash_address></sbl_mflash_address></pre>	[Required]	{to give sbl_mflash path}
-P <port_number></port_number>	[Required]	{UART3 port_number}
-F <file_location> <file_< td=""><td>offset> [Required]</td><td><pre>{file location and offset}</pre></td></file_<></file_location>	offset> [Required]	<pre>{file location and offset}</pre>
-F <file_location> <file_< td=""><td>offset> [Optional]</td><td></td></file_<></file_location>	offset> [Optional]	
-C	[Optional]	{to clear the flash memory}

For example, mflash -M "sbl_mflash" -P "5" -F "AppImage_BE" "0x80000" -F "sbl" "0x00" -C.

6. Put the board in qspi boot mode (change the switch settings) and restart it to boot the sbl and AppImage from flash.

NOTE:

- Note that AppImage and sbl here should be in Big Endian (BE).
- Root permission/admin rights might be required in several cases.

5.1

Texas

STRUMENTS

```
Sample Logs
[PC] File
                0
                       AppImage_BE
[PC] Offset
                0
                       0x80000
[PC] File
                1
                       sbl
[PC] Offset
                       0 \times 00
                1
[PC] com \\.\COM5
[PC] Put UART Boot Mode, make fresh UART connection & restart
[PC] Press Enter when done...
            = 115200
    Baud
    Parity = 2
    StopBits = 0
    ByteSize = 8
[PC] Opening serial port successful
[RBL]4 [RBL]1 [RBL]5 [RBL]1 [RBL]41 [RBL]4c [RBL]7 [RBL]2 [RBL]13 [RBL]2 [RBL]1 [RBL]0
[RBL]12 [RBL]15 [RBL]1 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0
[RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]14
[RBL]21 [RBL]1 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0
                                   [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0
[RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0
[RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0
[PC] Requesting the ASIC ID
[RBL]4 [RBL]1 [RBL]5 [RBL]1 [RBL]41 [RBL]4c [RBL]7 [RBL]2 [RBL]13 [RBL]2 [RBL]1 [RBL]0
[RBL]12 [RBL]15 [RBL]1 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0
[RBL]0 [RBL]0 [RBL]0
                    [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]14
[RBL]21 [RBL]1 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0
[RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0
                                  [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0
[RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0 [RBL]0
[PC] Requesting PERI_REQ mode
[PC] Sending SBL_MFLASH filesize.
[PC] Size of sbl_mflash = 105866
[PC] Sending SBL_MFLASH... Please wait
[PC] File Size = 105866
[PC] ##
[PC] Transfer Complete. Time = 10.000
[PC] Opening port for sbl_mflash.
           = 1200000
    Baud
    Parity = 0
    StopBits = 0
    ByteSize = 8
[PC] Opening serial port successful.
[PC] sbl_mflash switch On Request Sent.
[TDAxx] Utility mflash will Execute now.
[TDAxx] Setting up QSPI
[TDAxx] QSPI Spansion 4 bit Device type
[TDAxx] MID - 0x1
[TDAxx] DID - 0x18
[TDAxx] !!____TDAxx flashing utility___
                                     !!1
[TDAxx] Erasing entire QSPI Flash.. This takes 50-60 seconds.
0x008DAxx] Erase Completed!!!2
[PC] Download started[PC] File Size = 52368
[PC] #
[PC] Write File Completed.
0x80000me taken to download file = 0.002
[PC] Download started[PC] File Size = 6160892
[PC] Write File Completed.
[PC] Time taken to download file = 17.003
[TDAxx] Exiting.
```



mflash Algorithm

6 mflash Algorithm

- 1. Read the ASIC id from the ROM Bootloader (RBL)
- 2. Request the Peripherial Boot Mode
- 3. Send the sbl_mflash filesize
- 4. Send the sbl_mflash
- 5. Close the port and reopen it with UART settings of the sbl_mflash
- 6. Perform the two-way handshake
 - a. sbl_mflash as soon as it boots up will start sending character 'a' continuously
 - b. mflash.exe will wait for the character 'a' and upon receiving will send character '1'
 - c. sbl_mflash upon receiving '1' will send out character 'b' and get ready to proceed
 - d. mflash.exe upon receiving 'b' will get ready to transfer the files
- 7. sbl_mflash sends a request for the command.
- 8. mflash reads the request and sends the required actions like sending the filesize, file, offset, clear the flash, and so forth.
- 9. Upon completing the previous request, sbl_mflash waits for another request

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